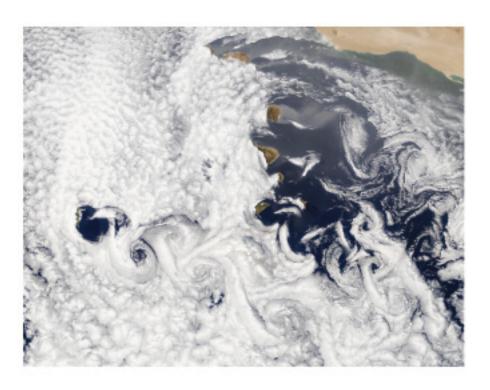
Geostrophy and Shallow-water model

Introduction to Geophysical Fluid Dynamics Physical and Numerical Aspects



Benoit Cushman-Roisin and Jean-Marie Beckers

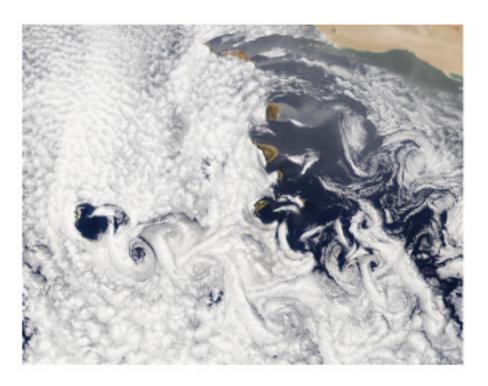
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Geostrophy and Shallow-water model

Further scaling of the primitive equations of motion

Introduction to Geophysical Fluid Dynamics

Physical and Numerical Aspects



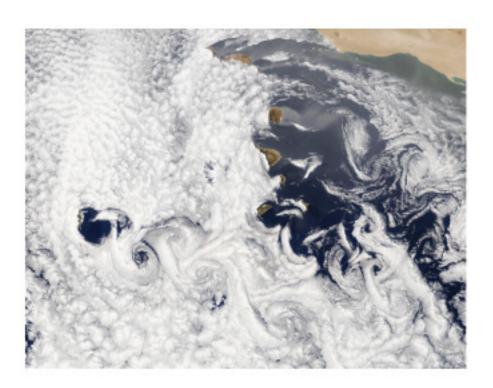
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Geostrophy and Shallow-water model

Introduction to Geophysical Fluid Dynamics Physical and Numerical Aspects

- Further scaling of the primitive equations of motion
- Dimensionless number and active dynamics



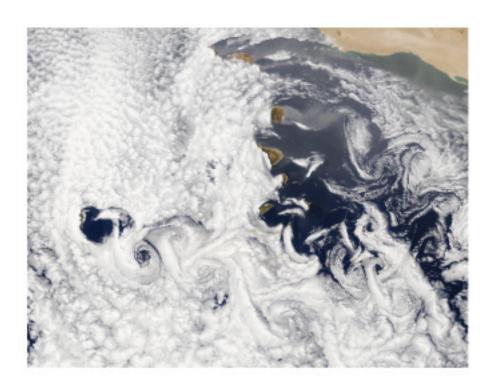
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Geostrophy and Shallow-water model

Introduction to Geophysical Fluid Dynamics Physical and Numerical Aspects

- Further scaling of the primitive equations of motion
- Dimensionless number and active dynamics
- Steady and homogenous flows (geostrophic flow)



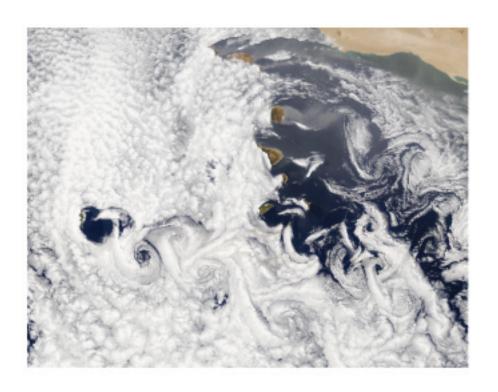
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Geostrophy and Shallow-water model

Introduction to Geophysical Fluid Dynamics Physical and Numerical Aspects

- Further scaling of the primitive equations of motion
- Dimensionless number and active dynamics
- Steady and homogenous flows (geostrophic flow)
- Properties of geostrophic flows



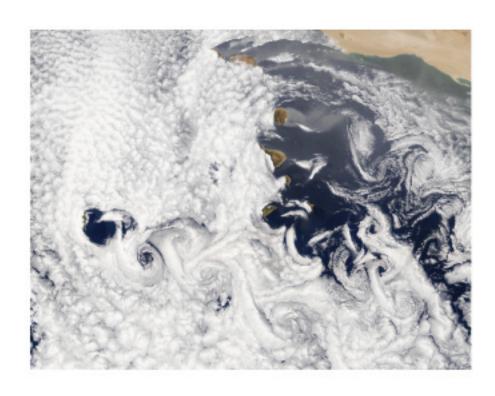
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Geostrophy and Shallow-water model

Introduction to Geophysical Fluid Dynamics Physical and Numerical Aspects

- Further scaling of the primitive equations of motion
- Dimensionless number and active dynamics
- Steady and homogenous flows (geostrophic flow)
- Properties of geostrophic flows
- Unsteady and homogenous flows (shallow water model)



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$$\begin{aligned} x - \text{momentum:} & \quad \frac{\partial u}{\partial t} + u \, \frac{\partial u}{\partial x} + v \, \frac{\partial u}{\partial y} + w \, \frac{\partial u}{\partial z} - fv = \\ & \quad - \frac{1}{\rho_0} \, \frac{\partial p}{\partial x} + \frac{\partial}{\partial x} \left(\mathcal{A} \frac{\partial u}{\partial x} \right) + \frac{\partial}{\partial y} \left(\mathcal{A} \frac{\partial u}{\partial y} \right) + \frac{\partial}{\partial z} \left(\nu_E \frac{\partial u}{\partial z} \right) \\ y - \text{momentum:} & \quad \frac{\partial v}{\partial t} + u \, \frac{\partial v}{\partial x} + v \, \frac{\partial v}{\partial y} + w \, \frac{\partial v}{\partial z} + fu = \\ & \quad - \frac{1}{\rho_0} \, \frac{\partial p}{\partial y} + \frac{\partial}{\partial x} \left(\mathcal{A} \frac{\partial v}{\partial x} \right) + \frac{\partial}{\partial y} \left(\mathcal{A} \frac{\partial v}{\partial y} \right) + \frac{\partial}{\partial z} \left(\nu_E \frac{\partial v}{\partial z} \right) \\ z - \text{momentum:} & \quad 0 = - \frac{\partial p}{\partial z} - \rho g \\ & \quad \text{continuity:} & \quad \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0 \\ & \quad \text{energy:} & \quad \frac{\partial \rho}{\partial t} + u \, \frac{\partial \rho}{\partial x} + v \, \frac{\partial \rho}{\partial y} + w \, \frac{\partial \rho}{\partial z} = \\ & \quad \frac{\partial}{\partial x} \left(\mathcal{A} \frac{\partial \rho}{\partial x} \right) + \frac{\partial}{\partial y} \left(\mathcal{A} \frac{\partial \rho}{\partial y} \right) + \frac{\partial}{\partial z} \left(\kappa_E \frac{\partial \rho}{\partial z} \right) \,, \end{aligned}$$

$$x - \text{momentum:} \qquad \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} - fv =$$

$$-\frac{1}{\rho_0} \frac{\partial p}{\partial x} + \frac{\partial}{\partial x} \left(\mathcal{A} \frac{\partial u}{\partial x} \right) + \frac{\partial}{\partial y} \left(\mathcal{A} \frac{\partial u}{\partial y} \right) + \frac{\partial}{\partial z} \left(\nu_E \frac{\partial u}{\partial z} \right)$$

$$x - \text{momentum:} \qquad \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} - fv =$$

$$-\frac{1}{\rho_0} \frac{\partial p}{\partial x} + \frac{\partial}{\partial x} \left(\mathcal{A} \frac{\partial u}{\partial x} \right) + \frac{\partial}{\partial y} \left(\mathcal{A} \frac{\partial u}{\partial y} \right) + \frac{\partial}{\partial z} \left(\nu_E \frac{\partial u}{\partial z} \right)$$

Scaling of terms

$$\frac{U}{T} \,, \quad \frac{U^2}{L} \,, \quad \frac{U^2}{L} \,, \quad \frac{WU}{H} \,, \quad \Omega U \,, \quad \frac{P}{\rho_0 L} \,, \quad \frac{\mathcal{A}U}{L^2} \,, \quad \frac{\nu_E U}{H^2}$$

$$x - \text{momentum:} \qquad \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} - fv =$$

$$-\frac{1}{\rho_0} \frac{\partial p}{\partial x} + \frac{\partial}{\partial x} \left(\mathcal{A} \frac{\partial u}{\partial x} \right) + \frac{\partial}{\partial y} \left(\mathcal{A} \frac{\partial u}{\partial y} \right) + \frac{\partial}{\partial z} \left(\nu_E \frac{\partial u}{\partial z} \right)$$

Scaling of terms

$$\frac{U}{T}, \quad \frac{U^2}{L}, \quad \frac{U^2}{L}, \quad \frac{WU}{H}, \quad \Omega U, \quad \frac{P}{\rho_0 L}, \quad \frac{AU}{L^2}, \quad \frac{\nu_E U}{H^2}$$

inertial terms

$$x - \text{momentum:} \qquad \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} - fv =$$

$$-\frac{1}{\rho_0} \frac{\partial p}{\partial x} + \frac{\partial}{\partial x} \left(\mathcal{A} \frac{\partial u}{\partial x} \right) + \frac{\partial}{\partial y} \left(\mathcal{A} \frac{\partial u}{\partial y} \right) + \frac{\partial}{\partial z} \left(\nu_E \frac{\partial u}{\partial z} \right)$$

Scaling of terms

$$\frac{U}{T}, \quad \frac{U^2}{L}, \quad \frac{U^2}{L}, \quad \frac{WU}{H}, \quad \Omega U, \quad \frac{P}{\rho_0 L}, \quad \frac{AU}{L^2}, \quad \frac{\nu_E U}{H^2}$$

inertial terms

rotation

$$x - \text{momentum:} \qquad \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} - fv =$$

$$-\frac{1}{\rho_0} \frac{\partial p}{\partial x} + \frac{\partial}{\partial x} \left(\mathcal{A} \frac{\partial u}{\partial x} \right) + \frac{\partial}{\partial y} \left(\mathcal{A} \frac{\partial u}{\partial y} \right) + \frac{\partial}{\partial z} \left(\nu_E \frac{\partial u}{\partial z} \right)$$

Scaling of terms

$$\frac{U}{T} \,, \quad \frac{U^2}{L} \,, \quad \frac{U^2}{L} \,, \quad \frac{WU}{H} \,, \quad \Omega U \,, \quad \frac{P}{\rho_0 L} \,, \quad \frac{\mathcal{A}U}{L^2} \,, \quad \frac{\nu_E U}{H^2}$$

inertial terms

rotation

$$x - \text{momentum:} \qquad \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} - fv =$$

$$-\frac{1}{\rho_0} \frac{\partial p}{\partial x} + \frac{\partial}{\partial x} \left(\mathcal{A} \frac{\partial u}{\partial x} \right) + \frac{\partial}{\partial y} \left(\mathcal{A} \frac{\partial u}{\partial y} \right) + \frac{\partial}{\partial z} \left(\nu_E \frac{\partial u}{\partial z} \right)$$

Scaling of terms

$$\left| \frac{U}{T} , \frac{U^2}{L} , \frac{U^2}{L} , \frac{WU}{H} , \right| \Omega U, \left| \frac{P}{\rho_0 L} , \frac{AU}{L^2} , \frac{\nu_E U}{H^2} \right|$$

inertial terms

rotation

frictional forces

divide by ΩU

$$x - \text{momentum:} \qquad \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} - fv =$$

$$-\frac{1}{\rho_0} \frac{\partial p}{\partial x} + \frac{\partial}{\partial x} \left(\mathcal{A} \frac{\partial u}{\partial x} \right) + \frac{\partial}{\partial y} \left(\mathcal{A} \frac{\partial u}{\partial y} \right) + \frac{\partial}{\partial z} \left(\nu_E \frac{\partial u}{\partial z} \right)$$

Scaling of terms

$$\frac{U}{T}$$
, $\frac{U^2}{L}$, $\frac{U^2}{L}$, $\frac{WU}{H}$, ΩU , $\frac{P}{\rho_0 L}$, $\frac{\mathcal{A}U}{L^2}$, $\frac{\nu_E U}{H^2}$

inertial terms

rotation

frictional forces

divide by ΩU

$$\frac{1}{\Omega T}$$
, $\frac{U}{\Omega L}$, $\frac{U}{\Omega L}$, $\frac{WL}{UH}$ · $\frac{U}{\Omega L}$, 1 , $\frac{P}{\rho_0 \Omega L U}$, $\frac{\mathcal{A}}{\Omega L^2}$, $\frac{\nu_E}{\Omega H^2}$

measuring the sizes of the terms in the equations

Typical Scales

• •	
Scale	Oceanic value
\overline{L}	$10 \text{ km} = 10^4 \text{ m}$
H	$100 \text{ m} = 10^2 \text{ m}$
T	$\geq 1 \mathrm{day} \simeq 9 \times 10^4 \mathrm{s}$
U	0.1 m/s
W	
P	variable
Δho	
Ω	10^{-5} s^{-1} .

inertial terms rotation frictional forces

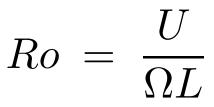
$$\frac{1}{\Omega T}$$
, $\frac{U}{\Omega L}$, $\frac{U}{\Omega L}$, $\frac{WL}{UH}$ · $\frac{U}{\Omega L}$

$$\frac{P}{\rho_0 \Omega L U}$$

$$\frac{\mathcal{A}}{\Omega L^2}$$
, $\frac{\nu_E}{\Omega H^2}$

measuring the sizes of the terms in the equations

Rossby Number advection/rotation



Typical Scales

Typical Scales	
Scale	Oceanic value
\overline{L}	$10 \text{ km} = 10^4 \text{ m}$
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T	$\geq 1 \mathrm{day} \simeq 9 \times 10^4 \mathrm{s}$
U	0.1 m/s
W	
P	variable
Δho	
Ω	10^{-5} s^{-1} .

inertial terms rotation

$$\frac{1}{\Omega T}$$
, $\frac{U}{\Omega L}$, $\frac{U}{\Omega L}$, $\frac{WL}{UH}$ $\frac{U}{\Omega L}$

$$\frac{P}{\rho_0 \Omega L U}$$

$$\frac{\mathcal{A}}{\Omega L^2} \; , \quad \frac{\nu_E}{\Omega H^2}$$

measuring the sizes of the terms in the equations

Rossby Number advection/rotation

$$Ro = \frac{U}{\Omega L}$$

Typical Scalac

Typical Scales		
Scale	Oceanic value	
\overline{L}	$10 \text{ km} = 10^4 \text{ m}$	
H	$100 \text{ m} = 10^2 \text{ m}$	
T	$\geq 1 \mathrm{day} \simeq 9 \times 10^4 \mathrm{s}$	
U	0.1 m/s	
W		
P	variable	
Δho		
Ω	10^{-5} s^{-1} .	
	·	

2 Ekman Number viscous force/rotation

$$Ek = \frac{\nu_E}{\Omega H^2}$$

inertial terms rotation

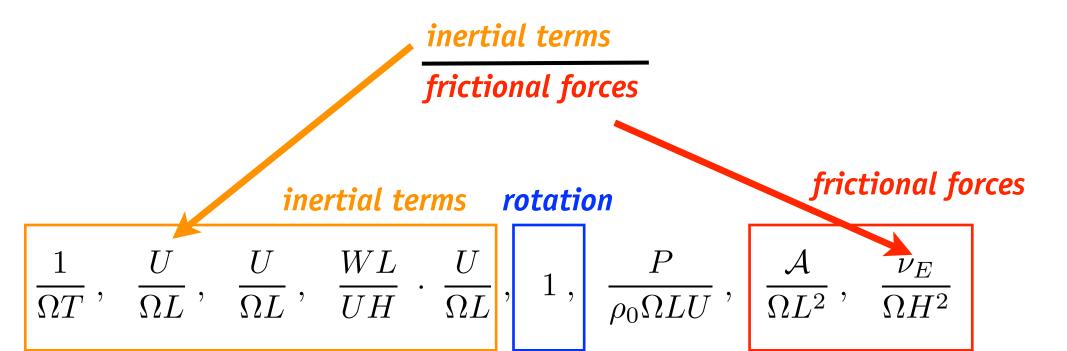
$$\frac{1}{\Omega T}$$
, $\frac{U}{\Omega L}$, $\frac{U}{\Omega L}$, $\frac{WL}{UH}$ · $\frac{U}{\Omega L}$

$$1\;,$$

$$\frac{P}{\rho_0 \Omega L U}$$

$$\frac{\mathcal{A}}{\Omega L^2} \; , \quad \frac{
u_E}{\Omega H^2}$$

measuring the sizes of the terms in the equations



measuring the sizes of the terms in the equations

3 Reynolds Number inertial forces/frictional forces

$$Re = \frac{UL}{\nu_E} = \frac{U}{\Omega L} \cdot \frac{\Omega H^2}{\nu_E} \cdot \frac{L^2}{H^2} = \frac{Ro}{Ek} \left(\frac{L}{H}\right)^2$$



inertial terms rotation

$$\frac{1}{\Omega T}$$
, $\frac{U}{\Omega L}$, $\frac{U}{\Omega L}$, $\frac{WL}{UH}$ $\frac{U}{\Omega L}$

$$\frac{P}{\rho_0 \Omega L U}$$
,

$$rac{\mathcal{A}}{\Omega L^2} \;, \quad rac{\overline{
u}_E}{\Omega H^2}$$

measuring the sizes of the terms in the equations

3 Reynolds Number inertial forces/frictional forces

high = turbulent flows

$$Re = \frac{UL}{\nu_E} = \frac{U}{\Omega L} \cdot \frac{\Omega H^2}{\nu_E} \cdot \frac{L^2}{H^2} = \frac{Ro}{Ek} \left(\frac{L}{H}\right)^2$$

inertial terms
frictional forces

inertial terms rotation

$$\frac{1}{\Omega T}$$
, $\frac{U}{\Omega L}$, $\frac{U}{\Omega L}$, $\frac{WL}{UH}$ $\frac{U}{\Omega L}$

$$\frac{P}{\rho_0 \Omega L U}$$
,

$$rac{\mathcal{A}}{\Omega L^2} \;, \quad rac{\overline{
u}_E}{\Omega H^2}$$

measuring the sizes of the terms in the equations

inertial terms rotation

$$\frac{1}{\Omega T}$$
, $\frac{U}{\Omega L}$, $\frac{U}{\Omega L}$, $\frac{WL}{UH}$ · $\frac{U}{\Omega L}$

$$\frac{P}{\rho_0 \Omega L U}$$

$$\frac{\mathcal{A}}{\Omega L^2} \; , \quad \frac{\nu_E}{\Omega H^2}$$

measuring the sizes of the terms in the equations

4 Richardson Number

inertial terms rotation

$$rac{1}{\Omega T} \; , \quad rac{U}{\Omega L} \; , \quad rac{U}{\Omega L} \; , \quad rac{WL}{UH} \; \cdot \; rac{U}{\Omega L}$$

$$\frac{P}{\rho_0 \Omega L U}$$

$$rac{\mathcal{A}}{\Omega L^2} \; , \quad rac{
u_E}{\Omega H^2}$$

measuring the sizes of the terms in the equations

4 Richardson Number

$$Ri = \frac{gH\Delta\rho}{\rho_0 U^2}$$

inertial terms rotation

$$\frac{1}{\Omega T}$$
, $\frac{U}{\Omega L}$, $\frac{U}{\Omega L}$, $\frac{WL}{UH}$ $\frac{U}{\Omega L}$

$$\frac{P}{\rho_0 \Omega L U}$$
,

$$\frac{\mathcal{A}}{\Omega L^2} \; , \quad \frac{
u_E}{\Omega H^2}$$

measuring the sizes of the terms in the equations

4 Richardson Number

Available Potential Energy (APE)

$$Ri = rac{gH\Delta
ho}{
ho_0 U^2}$$
 Kinetic Energy (KE)

inertial terms rotation

$$\frac{1}{\Omega T}$$
, $\frac{U}{\Omega L}$, $\frac{U}{\Omega L}$, $\frac{WL}{UH}$ · $\frac{U}{\Omega L}$

$$1, \frac{P}{\rho_0 \Omega L U}$$

$$\frac{\mathcal{A}}{\Omega L^2} \; , \quad \frac{
u_E}{\Omega H^2}$$

inertial terms rotation

$$\frac{1}{\Omega T}$$
, $\frac{U}{\Omega L}$, $\frac{U}{\Omega L}$, $\frac{WL}{UH}$ \cdot $\frac{U}{\Omega L}$

$$\frac{P}{\rho_0 \Omega L U}$$
,

$$\frac{\mathcal{A}}{\Omega L^2} \; , \quad \frac{
u_E}{\Omega H^2}$$

$$Ro_T \ll 1$$
, $Ro \ll 1$, $Ek \ll 1$

inertial terms rotation

$$\frac{1}{\Omega T}$$
, $\frac{U}{\Omega L}$, $\frac{U}{\Omega L}$, $\frac{WL}{UH}$ · $\frac{U}{\Omega L}$

$$\frac{P}{\rho_0 \Omega L U}$$

$$rac{\mathcal{A}}{\Omega L^2} \; , \quad rac{
u_E}{\Omega H^2}$$

$$Ro_T \ll 1$$
, $Ro \ll 1$, $Ek \ll 1$

$$x - \text{momentum:} \qquad \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} - fv =$$

$$-\frac{1}{\rho_0} \frac{\partial p}{\partial x} + \frac{\partial}{\partial x} \left(\mathcal{A} \frac{\partial u}{\partial x} \right) + \frac{\partial}{\partial y} \left(\mathcal{A} \frac{\partial u}{\partial y} \right) + \frac{\partial}{\partial z} \left(\nu_E \frac{\partial u}{\partial z} \right)$$

inertial terms rotation

$$\frac{1}{\Omega T}$$
, $\frac{U}{\Omega L}$, $\frac{U}{\Omega L}$, $\frac{WL}{UH}$ · $\frac{U}{\Omega L}$, 1 , $\frac{P}{\rho_0 \Omega L U}$, $\frac{\mathcal{A}}{\Omega L^2}$, $\frac{\nu_E}{\Omega H^2}$

$$Ro_T \ll 1$$
, $Ro \ll 1$, $Ek \ll 1$

$$x$$
 – momentum:

$$\begin{array}{c} \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} - fv = \\ -\frac{1}{\rho_0} \frac{\partial p}{\partial x} + \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} \right) + \frac{\partial}{\partial y} \left(\frac{\partial u}{\partial y} \right) + \frac{\partial}{\partial z} \left(\frac{\partial u}{\partial z} \right) \\ \text{small} \end{array}$$

inertial terms rotation

$$\frac{1}{\Omega T}$$
, $\frac{U}{\Omega L}$, $\frac{U}{\Omega L}$, $\frac{WL}{UH}$ · $\frac{U}{\Omega L}$, 1 , $\frac{P}{\rho_0 \Omega L U}$, $\frac{\mathcal{A}}{\Omega L^2}$, $\frac{\nu_E}{\Omega H^2}$

$$\frac{P}{\rho_0 \Omega L U}$$

$$rac{\mathcal{A}}{\Omega L^2} \; , \quad rac{
u_E}{\Omega H^2}$$

$$Ro_T \ll 1$$
, $Ro \ll 1$, $Ek \ll 1$

$$x$$
 – momentum:

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} - fv =$$

$$-\frac{1}{\rho_0} \frac{\partial p}{\partial x} + \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} \right) + \frac{\partial}{\partial y} \left(\frac{\partial u}{\partial y} \right) + \frac{\partial}{\partial z} \left(\frac{\partial u}{\partial z} \right)$$

$$\frac{\partial u}{\partial x} + v \frac{\partial u}{\partial x} + w \frac{\partial u}{\partial z} - fv =$$

$$\frac{\partial u}{\partial x} + v \frac{\partial u}{\partial x} + w \frac{\partial u}{\partial z} - fv =$$

$$\frac{\partial u}{\partial x} + v \frac{\partial u}{\partial x} + w \frac{\partial u}{\partial z} - fv =$$

$$\frac{\partial u}{\partial x} + v \frac{\partial u}{\partial x} + w \frac{\partial u}{\partial z} - fv =$$

$$\frac{\partial u}{\partial x} + v \frac{\partial u}{\partial x} + w \frac{\partial u}{\partial z} - fv =$$

$$\frac{\partial u}{\partial x} + v \frac{\partial u}{\partial x} + w \frac{\partial u}{\partial x} - fv =$$

$$\frac{\partial u}{\partial x} + v \frac{\partial u}{\partial x} + w \frac{\partial u}{\partial x} - fv =$$

$$\frac{\partial u}{\partial x} + v \frac{\partial u}{\partial x} + w \frac{\partial u}{\partial x} - fv =$$

$$\frac{\partial u}{\partial x} + v \frac{\partial u}{\partial x} + w \frac{\partial u}{\partial x} - fv =$$

$$\frac{\partial u}{\partial x} + v \frac{\partial u}{\partial x} + w \frac{\partial u}{\partial x} - fv =$$

$$\frac{\partial u}{\partial x} + v \frac{\partial u}{\partial x} + w \frac{\partial u}{\partial x} - fv =$$

$$\frac{\partial u}{\partial x} + v \frac{\partial u}{\partial x} + w \frac{\partial u}{\partial x} - fv =$$

$$\frac{\partial u}{\partial x} + v \frac{\partial u}{\partial x} + w \frac{\partial u}{\partial x} - fv =$$

$$\frac{\partial u}{\partial x} + v \frac{\partial u}{\partial x} + w \frac{\partial u}{\partial x} - fv =$$

$$\frac{\partial u}{\partial x} + v \frac{\partial u}{\partial x} + w \frac{\partial u}{\partial x} + w \frac{\partial u}{\partial x} - fv =$$

$$\frac{\partial u}{\partial x} + v \frac{\partial u}{\partial x} + w \frac{\partial u}$$

inertial terms rotation

$$\frac{1}{\Omega T}$$
, $\frac{U}{\Omega L}$, $\frac{U}{\Omega L}$, $\frac{WL}{UH}$ · $\frac{U}{\Omega L}$

$$1, \frac{P}{\rho_0 \Omega L U}$$

$$\frac{\mathcal{A}}{\Omega L^2} \; , \quad \frac{\nu_E}{\Omega H^2}$$

$$Ro_T \ll 1$$
, $Ro \ll 1$, $Ek \ll 1$

$$x - \text{momentum:} \qquad \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial s_{\text{small}}} + v \frac{\partial u}{\partial t} + w \frac{\partial u}{\partial s_{\text{small}}} - fv = \begin{bmatrix} -\frac{1}{\rho_0} \frac{\partial p}{\partial x} + \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + v \frac{\partial u}{\partial z} \end{bmatrix}$$

$$z - \text{momentum:} \qquad 0 = -\frac{\partial p}{\partial z} - \rho g$$

$$\text{continuity:} \qquad \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

$$\text{energy:} \qquad \frac{\partial \rho}{\partial t} + u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} = \frac{\partial \rho}{\partial x} \left(A \frac{\partial \rho}{\partial x} \right) + \frac{\partial \sigma}{\partial y} \left(A \frac{\partial \rho}{\partial y} \right) + \frac{\partial \sigma}{\partial z} \left(\kappa_E \frac{\partial \rho}{\partial z} \right)$$

$$Ro_T \ll 1, \quad Ro \ll 1, \quad Ek \ll 1,$$
 $\rho = 0$ (no density variation)

$$x - \text{momentum:} \qquad \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} - fv = \\ -\frac{1}{\rho_0} \frac{\partial p}{\partial x} + \frac{\partial}{\partial x} \left(A \frac{\partial u}{\partial x} \right) + \frac{\partial}{\partial y} \left(A \frac{\partial u}{\partial y} \right) + \frac{\partial}{\partial z} \left(\nu_E \frac{\partial u}{\partial z} \right) \\ z - \text{momentum:} \qquad 0 = -\frac{\partial p}{\partial z} - \rho g \\ \text{continuity:} \qquad \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0 \\ \text{energy:} \qquad \frac{\partial \rho}{\partial t} + u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} = \\ \frac{\partial}{\partial x} \left(A \frac{\partial \rho}{\partial x} \right) + \frac{\partial}{\partial u} \left(A \frac{\partial \rho}{\partial u} \right) + \frac{\partial}{\partial z} \left(\kappa_E \frac{\partial \rho}{\partial z} \right) \\ \end{cases}$$

$$Ro_T \ll 1, \quad Ro \ll 1, \quad Ek \ll 1,$$
 $ho = 0$ (no density variation)

$$x - \text{momentum:} \qquad \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} - fv = \frac{1}{\rho_0} \frac{\partial p}{\partial x} + \frac{\partial u}{\partial x} \left(A \frac{\partial u}{\partial x} \right) + \frac{\partial u}{\partial y} \left(A \frac{\partial u}{\partial y} \right) + \frac{\partial u}{\partial z} \left(v_E \frac{\partial u}{\partial z} \right) = \frac{\partial p}{\partial x} + \frac{\partial u}{\partial y} + \frac{\partial u}{\partial z} = 0$$

$$continuity: \qquad \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

$$energy: \qquad \frac{\partial p}{\partial t} + u \frac{\partial p}{\partial x} + v \frac{\partial p}{\partial y} + w \frac{\partial p}{\partial z} = \frac{\partial p}{\partial x} \left(A \frac{\partial p}{\partial x} \right) + \frac{\partial u}{\partial x} \left(A \frac{\partial p}{\partial y} \right) + \frac{\partial u}{\partial z} \left(A \frac{\partial p}{\partial y} \right) = \frac{\partial p}{\partial x} \left(A \frac{\partial p}{\partial x} \right) + \frac{\partial u}{\partial z} \left(A \frac{\partial p}{\partial y} \right) + \frac{\partial u}{\partial z} \left(A \frac{\partial p}{\partial y} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) + \frac{\partial u}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial p}{\partial z} \right) = \frac{\partial p}{\partial z} \left(A \frac{\partial$$

$$Ro_T \ll 1$$
, $Ro \ll 1$, $Ek \ll 1$. $\rho = 0$ (no density variation)

$$-fv = -\frac{1}{\rho_0} \frac{\partial p}{\partial x}$$

$$+fu = -\frac{1}{\rho_0} \frac{\partial p}{\partial y}$$
 homogeneous flow
$$0 = -\frac{1}{\rho_0} \frac{\partial p}{\partial z}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0,$$

Properties of Geostrophic homogeneous flows

$$u = \frac{-1}{\rho_0 f} \frac{\partial p}{\partial y}, \quad v = \frac{+1}{\rho_0 f} \frac{\partial p}{\partial x}$$

Properties of Geostrophic homogeneous flows

geostrophic flows follow lines of constant pressure = *isobars*

$$u = \frac{-1}{\rho_0 f} \frac{\partial p}{\partial y}, \quad v = \frac{+1}{\rho_0 f} \frac{\partial p}{\partial x}.$$

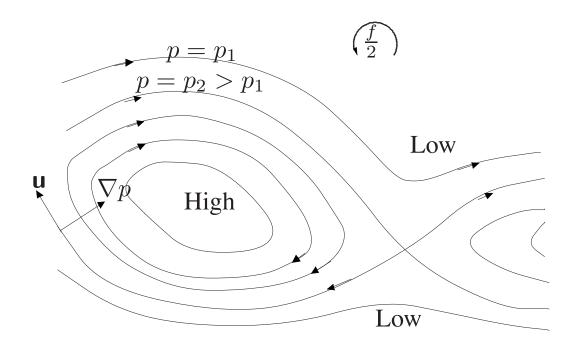


Figure 7-1 Example of geostrophic flow. The velocity vector is everywhere parallel to the lines of equal pressure. Thus, pressure contours act as streamlines. In the Northern Hemisphere (as pictured here), the fluid circulates with the high pressure on its right. The opposite holds for the Southern Hemisphere.

Properties of Geostrophic homogeneous flows

$$-fv = -\frac{1}{\rho_0} \frac{\partial p}{\partial x}$$

$$+fu = -\frac{1}{\rho_0} \frac{\partial p}{\partial y}$$

$$0 = -\frac{1}{\rho_0} \frac{\partial p}{\partial z}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0,$$

$$\frac{\partial}{\partial z} \begin{pmatrix} -fv &=& -\frac{1}{\rho_0} \frac{\partial p}{\partial x} \\ +fu &=& -\frac{1}{\rho_0} \frac{\partial p}{\partial y} \\ 0 &=& -\frac{1}{\rho_0} \frac{\partial p}{\partial z} \end{pmatrix}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0,$$

$$\frac{\partial}{\partial z} \begin{pmatrix} -fv & = & -\frac{1}{\rho_0} \frac{\partial p}{\partial x} \\ +fu & = & -\frac{1}{\rho_0} \frac{\partial p}{\partial y} \\ 0 & = & -\frac{1}{\rho_0} \frac{\partial p}{\partial z} \end{pmatrix}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0,$$
no vertical shear

$$-f\frac{\partial v}{\partial z} = -\frac{1}{\rho_0} \frac{\partial}{\partial z} \left(\frac{\partial p}{\partial x} \right) = -\frac{1}{\rho_0} \frac{\partial}{\partial x} \left(\frac{\partial p}{\partial z} \right) = 0$$

$$\frac{\partial}{\partial z} \begin{pmatrix} -fv &=& -\frac{1}{\rho_0} \frac{\partial p}{\partial x} \\ +fu &=& -\frac{1}{\rho_0} \frac{\partial p}{\partial y} \\ 0 &=& -\frac{1}{\rho_0} \frac{\partial p}{\partial z} \end{pmatrix}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} &=& 0,$$

$$-f \frac{\partial v}{\partial z} = -\frac{1}{\rho_0} \frac{\partial}{\partial z} \left(\frac{\partial p}{\partial x} \right) = -\frac{1}{\rho_0} \frac{\partial}{\partial x} \left(\frac{\partial p}{\partial z} \right) = 0$$

$$-fv = -\frac{1}{\rho_0} \frac{\partial p}{\partial x}$$

$$+fu = -\frac{1}{\rho_0} \frac{\partial p}{\partial y}$$

$$0 = -\frac{1}{\rho_0} \frac{\partial p}{\partial z}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0,$$

$$-fv = -\frac{1}{\rho_0} \frac{\partial p}{\partial x}$$

$$+fu = -\frac{1}{\rho_0} \frac{\partial p}{\partial y}$$

$$0 = -\frac{1}{\rho_0} \frac{\partial p}{\partial z}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0,$$

$$\frac{\partial}{\partial x} \begin{pmatrix} -fv & = -\frac{1}{\rho_0} \frac{\partial p}{\partial x} \\ +fu & = -\frac{1}{\rho_0} \frac{\partial p}{\partial y} \end{pmatrix}$$

$$0 & = -\frac{1}{\rho_0} \frac{\partial p}{\partial z}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} & = 0,$$

$$\frac{\partial}{\partial x} \begin{pmatrix} -fv & = & -\frac{1}{\rho_0} \frac{\partial p}{\partial x} \\ +fu & = & -\frac{1}{\rho_0} \frac{\partial p}{\partial y} \end{pmatrix}$$

$$0 & = & -\frac{1}{\rho_0} \frac{\partial p}{\partial z}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0,$$

$$non-divergent$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = -\frac{\partial}{\partial x} \left(\frac{1}{\rho_0 f} \frac{\partial p}{\partial y} \right) + \frac{\partial}{\partial y} \left(\frac{1}{\rho_0 f} \frac{\partial p}{\partial x} \right) = 0$$

$$\frac{\partial}{\partial x} \begin{pmatrix} -fv & = & -\frac{1}{\rho_0} \frac{\partial p}{\partial x} \\ +fu & = & -\frac{1}{\rho_0} \frac{\partial p}{\partial y} \end{pmatrix}$$

$$0 & = & -\frac{1}{\rho_0} \frac{\partial p}{\partial z}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0,$$

$$non-divergent$$

$$\frac{\partial w}{\partial z} = 0$$

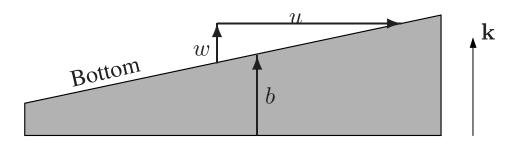


Figure 7-3 Schematic view of a flow over a sloping bottom. A vertical velocity must accompany flow across isobaths.

$$\frac{\partial w}{\partial z} = 0$$

if f-plane

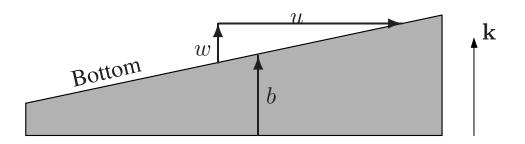


Figure 7-3 Schematic view of a flow over a sloping bottom. A vertical velocity must accompany flow across isobaths.

therefore flow is permitted only along isobaths

$$\frac{\partial w}{\partial z} = 0$$

if f-plane

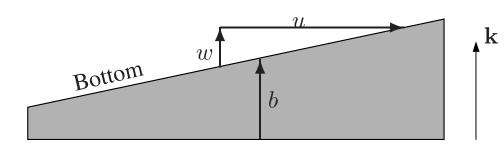
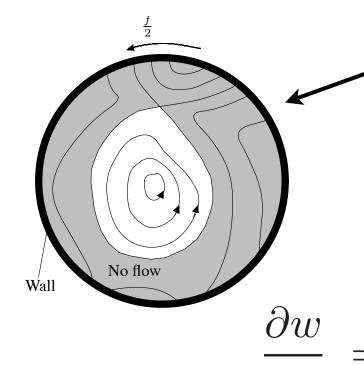


Figure 7-3 Schematic view of a flow over a sloping bottom. A vertical velocity must accompany flow across isobaths.



therefore flow is permitted only along isobaths

Figure 7-4 Geostrophic flow in a closed domain and over irregular topography. Solid lines are isobaths (contours of equal depth). Flow is permitted only along closed isobaths

$$-fv = -\frac{1}{\rho_0} \frac{\partial p}{\partial x}$$

$$+fu = -\frac{1}{\rho_0} \frac{\partial p}{\partial y}$$

$$0 = -\frac{1}{\rho_0} \frac{\partial p}{\partial z}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0,$$

homogeneous flow

$$-fv = -\frac{1}{\rho_0} \frac{\partial p}{\partial x}$$

$$+fu = -\frac{1}{\rho_0} \frac{\partial p}{\partial y}$$

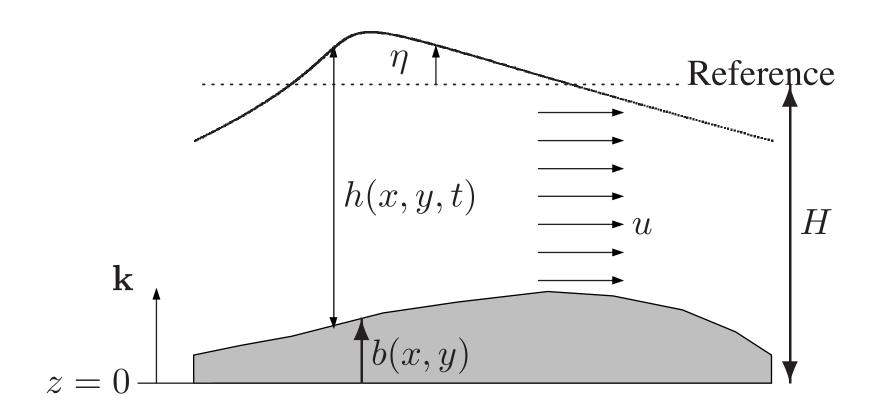
$$0 = -\frac{1}{\rho_0} \frac{\partial p}{\partial z}$$

homogeneous flow

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0,$$

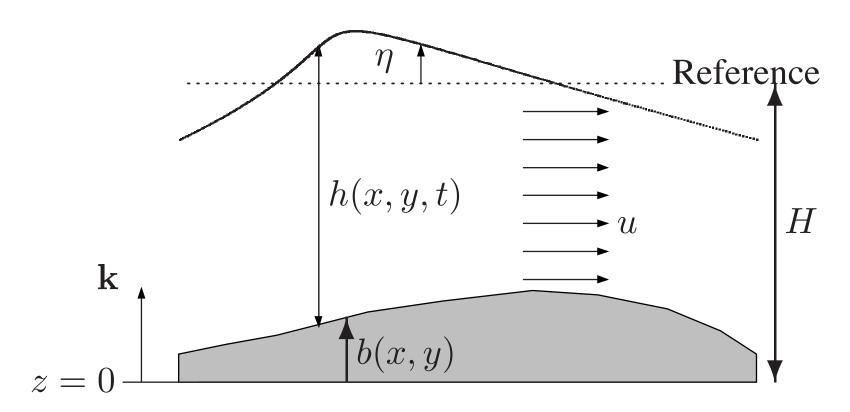
if pressure only a function of the sea level

$$p = \rho_0 g \eta$$



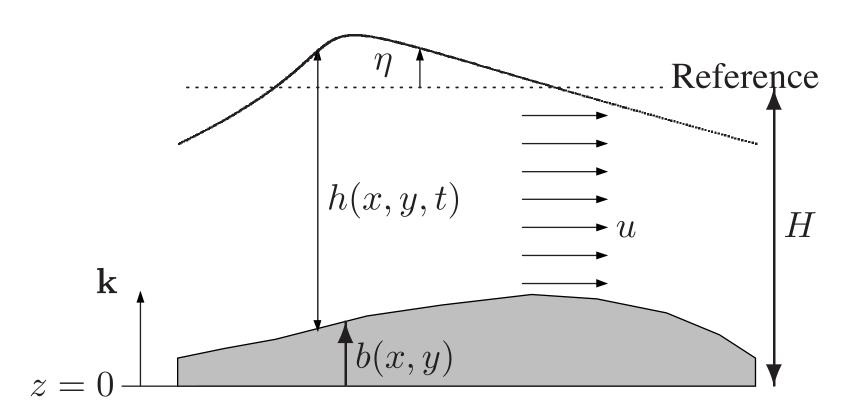
if pressure only a function of the sea level

$$p = \rho_0 g \eta$$



re-write the continuity equation for the layer velocity

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$



re-write the continuity equation for the layer velocity

$$\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0\right) \int_{b}^{b+h} dz$$

re-write the continuity equation for the layer velocity

$$\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y}\right) \int_{b}^{b+h} dz + [w]_{b}^{b+h}$$

$$w(z = b + h) = \frac{\partial}{\partial t}(b + h) + u\frac{\partial}{\partial x}(b + h) + v\frac{\partial}{\partial y}(b + h)$$

$$= \frac{\partial\eta}{\partial t} + u\frac{\partial\eta}{\partial x} + v\frac{\partial\eta}{\partial y}$$

$$w(z = b) = u\frac{\partial b}{\partial x} + v\frac{\partial b}{\partial y}.$$
boundary conditions

re-write the continuity equation for the layer velocity

$$\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y}\right) \int_{b}^{b+h} dz + [w]_{b}^{b+h}$$

$$w(z = b + h) = \frac{\partial}{\partial t}(b + h) + u\frac{\partial}{\partial x}(b + h) + v\frac{\partial}{\partial y}(b + h)$$

$$= \frac{\partial\eta}{\partial t} + u\frac{\partial\eta}{\partial x} + v\frac{\partial\eta}{\partial y}$$

$$w(z = b) = u\frac{\partial b}{\partial x} + v\frac{\partial b}{\partial y}.$$
boundary conditions

where
$$\eta = b + h - H$$

re-write the continuity equation for the layer velocity

$$\left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y}\right) \int_b^{b+h} dz + [w]_b^{b+h}$$

$$\begin{split} w(z = b + h) &= \frac{\partial}{\partial t}(b + h) + u\frac{\partial}{\partial x}(b + h) + v\frac{\partial}{\partial y}(b + h) \\ &= \frac{\partial\eta}{\partial t} + u\frac{\partial\eta}{\partial x} + v\frac{\partial\eta}{\partial y} \\ w(z = b) &= u\frac{\partial b}{\partial x} + v\frac{\partial b}{\partial y} \;. \end{split}$$
 boundary conditions

where
$$\eta = b + h - H$$

re-write the continuity equation for the layer velocity

$$\frac{\partial \eta}{\partial t} + \frac{\partial}{\partial x}(hu) + \frac{\partial}{\partial y}(hv) = 0$$

NEW continuity equation!

$$- fv = -\frac{1}{\rho_0} \frac{\partial p}{\partial x} + fu = -\frac{1}{\rho_0} \frac{\partial p}{\partial y}$$

$$\frac{\partial \eta}{\partial t} + \frac{\partial}{\partial x}(hu) + \frac{\partial}{\partial y}(hv) = 0$$

if pressure only a function of the sea level

$$p = \rho_0 g \eta$$

$$- f v = -\frac{1}{\rho_0} \frac{\partial p}{\partial x}$$

$$+ f u = -\frac{1}{\rho_0} \frac{\partial p}{\partial y}$$

$$\frac{\partial \eta}{\partial t} + \frac{\partial}{\partial x} (h u) + \frac{\partial}{\partial y} (h v) = 0$$

$$-fv = -g \frac{\partial \eta}{\partial x}$$

$$+ fu = -g \frac{\partial \eta}{\partial y}$$

$$\frac{\partial \eta}{\partial t} + \frac{\partial}{\partial x}(hu) + \frac{\partial}{\partial y}(hv) = 0$$

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} - fv = -g \frac{\partial \eta}{\partial x}$$

$$\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + fu = -g \frac{\partial \eta}{\partial y}$$

$$\frac{\partial \eta}{\partial t} + \frac{\partial \eta}{\partial x} (hu) + \frac{\partial \eta}{\partial y} (hv) = 0$$

shallow-water model or barotropic equations

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} - fv = -g \frac{\partial \eta}{\partial x}$$

$$\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + fu = -g \frac{\partial \eta}{\partial y}$$

$$\frac{\partial \eta}{\partial t} + \frac{\partial}{\partial x} (hu) + \frac{\partial}{\partial y} (hv) = 0$$

shallow-water model or barotropic equations

describe unsteady motions of a 2D uniform density layer

or

of the depth average motion

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} - fv = -g \frac{\partial \eta}{\partial x}$$

$$\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + fu = -g \frac{\partial \eta}{\partial y}$$

$$\frac{\partial \eta}{\partial t} + \frac{\partial}{\partial x} (hu) + \frac{\partial}{\partial y} (hv) = 0$$